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# BOOKS

Control and Dynamic Systems, Takahashi, M. J. Rubins, and D. A. Auslander, Addison-Wesley Publishing Co. (1970). 800 pages, \$17.50.

This is a well-thought-out and wellexecuted book. However, as the pre-face indicates, "this is a book for mechanical engineers, although it is also applicable for electrical and chemical engineers." Thus, most of the examples and discussions deal with systems and problems that are not, except from a conceptual point of view, of direct interest to chemical engineers. Nevertheless, there are sufficient ideas and developments in this work to suggest that the chemical engineer would find the book worthwhile, at least as an excellent secondary reference.

The book is divided into four main sections. These are (1) linear system theory, (2) formulation of dynamic systems, (3) control of linear systems, and (4) nonlinear, stochastic, optimal control and logic systems. Section (1) is really a state vector approach to the representation of lumped-parameter systems. It includes material on signalflow diagrams, Laplace- and z-transforms, diagonalization method, difference equations, the matrix exponential, controllability and observability, and all aspects of stability of linear systems including Liapunov theory. All in all, this is an excellent section on most aspects of linear systems and their analysis.

Section (2) then proceeds to the development or identification of models of lumped- and distributed-parameter systems via many physical processes. Of specific interest to the chemical engineer is the material on heat exchanger and percolation systems. The latter, in particular, has application to flow in packed beds and is extremely well done. The whole chapter on distributed-parameter systems is, in fact, well developed and of more than pass-

ing interest.

Section (3) deals with linear control systems and includes many aspects of classical process control and frequency response techniques. It also develops the theory of feed-forward control, of decoupling techniques for linear systems, and of computer directed control. Special interest lies in model control of distributed-parameter systems and of linear-quadratic control as developed through the Liapunov formulation rather than standard minimum principle techniques.

Section (4) covers a variety of topics such as the analysis of oscillating nonlinear systems (limit cycles), nonlinear stability via the Liapunov formulation, minimum time control and dynamic programming, Kalman filtering, and

switching algebra.

It is apparent from this brief analysis of the contents that the book contains a wealth of information. Coupled with excellent examples and problems (a solution manual is available) and the comparatively nonrigorous mathematical developments is a very large set of excellent drawings and flow diagrams.

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